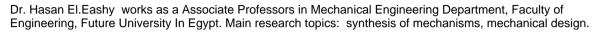


Basic Information:

Name: Hasan Eleashy

Title: Associate Professors





Education:					
Certificate	Major	University	Year		
PhD	Department of Mechanical Engineering	Elmansoura University - Faculty of Engineerin	2014		
Masters	Mechanical Design	Mansoura - Egypt	2006		
Bachelor	Production Engineering	Mansoura - Egypt	2000		

Teaching Experience:						
Name Of Organization	Position	From Date	To Date			
FUE	Associate Professor	18/02/2007	Current			
Organization	Radio & T.V Union	01/07/2002	31/01/2007			

Researches / Publications:

Parametric optimization of fillet radius for V6-engin crankshaft under static loading

Optimal TID Tracking Control for Industrial Delta Robot Based on Harmony search

Enhancing Wind Turbine Performance Using Flow Control Techniques: A Mini Review

Design and Control of Delta Robot (mini review)

Minimizing Buoyancy Factor of Metallic Pressure-Hull Subjected to Hydrostatic Pressure

A New Methodology for Type Synthesis of Planar Linkages for Exoskeletons up to Five Angular Outputs

A new atlas for 8-bar kinematic chains with up to 3 prismatic pairs using Joint Sorting Code

A new atlas for 8-bar kinematic chains with up to 3 prismatic pairs using Joint Sorting

Complete Atlas For Mechanically Constrained Double 3R Chains

USING STRUCTURAL CODE TECHNIQUE FOR ENUMERATION OF 6-BAR LINKAGES FROM OPEN 4-BAR CHAIN

Structural Synthesis of Mechanically Constrained Single Loop 6-Bar Chain

Synthesis of One Degree-Of-Freedom 6-Bar Linkages from Three Degree-Of-Freedom Open 4-Bar Chain Using Structural Code Technique

STRUCTURAL SYNTHESIS OF MECHANICALLY CONSTRAINED SINGLE LOOP 6-BAR CHAIN FROM DOUBLE 3R CHAIN

Structural Synthesis of 6 Bar Mechanisms as Mechanically Constrained 3R Chains

Structural Synthesis And Enumeration of Epicyclic Gear Mechanisms

Structural Synthesis and Enumeration of Epicyclic Gear Mechanisms Up To 12-Links Using Acyclic Graph Method

Graphical Code Method as New Technique for Topological Synthesis of Epicyclic Gear Mechanisms

New Approach for Enumeration and Evaluation of n-Links Epicyclic Gear Mechanisms

Using Acyclic graph Method and elementary Gear Units for Sketching Epicyclic Gear Mechanisms



ASME Turbo-Expo2006 conference,

PEDD7 Ain Shams Engineering conference,

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Engineering Assiut University Conference

Optimal TID Tracking Control for Industrial Delta Robot Based on Harmony search

Design and Control of Delta Robot

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Award	Donor	Date
NA	NA	01/01/2014